

# InterprocStack analyzer for recursive programs with finite-type and numerical variables

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## 1 Invoking InterprocStack

You can try an online version there.

The executable (`interprocstack` or `interprocstack.opt`) is invoked as follows:

```
interprocstack <options> <inputfile>
```

The input file should be a valid “Simple” program. The options are:

`-debug <int>` debug level, from 0 (lowest) to 4 (highest). Default is 0.

`-domain {box|octagon|polka|polkastrict|polkaeq|ppl|pplstrict|pplgrid|polkagrid}`  
abstract domain to use (default: `polka`). All domains supported by the Apron library can be specified:

box	intervals
octagon	octagons
polka,ppl	topologically closed convex polyhedra
polkastrict,pplstrict	possibly non-closed convex polyhedra
polkaeq	linear equalities
pplgrid	linear congruences
polkagrid	reduced product of linear congruences and Polka convex polyhedra

`-depth <int>` depth of recursive iterations (default 2, may only be more). See Fixpoint library documentation.

- guided <bool> if true, guided analysis of Gopand and Reprs (default: false). See Analyzer
- widening <bool><int><int><int> specifies usage of widening first heuristics, delay and frequency of widening, and nb. of descending steps (default: false 1 1 2). See Fixpoint
- analysis <('f'|'b')+> sequence of forward and backward analyses to perform (default "f")

## 2 The “Simple” language

Program Sample:

```

/* Procedure definition */
proc MC(b:bool,n:int) returns (r:int)
var t1:int, t2:int, b1:bool;
begin
  if (b != (n>100)) then fail; endif;
  if b then
    r = n-10;
  else
    t1 = n + 11;
    b1 = t1>100;
    t2 = MC1(b1,t1);
    b1 = t2>100;
    r = MC1(b1,t2);
  endif;
end
/* Main procedure */
var x:int, y:int,b:bool;
begin
  b = x>100;
  y = MC(b,x);
end

```

### 2.1 Syntax and informal semantics

#### 2.1.1 Program.

<pre> &lt;program&gt; ::= [typedef &lt;type_def&gt;+ ]              &lt;procedure_def&gt;*              [var &lt;vars_decl&gt; ; ]              begin &lt;statement&gt;+ end &lt;type_def&gt; ::= id = enum { id ( , id)* } ; &lt;procedure_def&gt; ::= proc id ( &lt;vars_decl&gt; ) returns ( &lt;vars_decl&gt; )                   [var &lt;vars_decl&gt; ; ]                   begin &lt;statement&gt;+ end </pre>	<pre> enumerated types definition definition of procederes local variables of the main procedure body of the main procedure signature, with names of input and output formal parameter (other) local variables body </pre>
------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------	----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------

A procedure definition first declares a list of formal input parameters, then a list of formal output parameters (which are local variables that defines the tuple of returned values), then a list of local variables, and then a body. A procedure ends with its last statement.

```

<vars_decl> ::=  $\epsilon$  | id : <type> ( , id : <type> )*
<type> ::= bool           Boolean type
         | uint [<integer>] unsigned integers encoded with <integer> bits
         | sint [<integer>] signed integers encoded with <integer> bits
         | id              Name of an enumerated type
         | int | real      numerical types

```

Variables are either of finite-type, or unbounded integer or real type. Finite types includes Boolean, bounded integers encoded with the given number of bits, and enumerated types. Real variables can behave as floating-point variables by modifying the exact semantics of arithmetic operations (see below).

### 2.1.2 Instructions.

```

<statement> ::= skip ;
             | halt ;
             | fail ;
             | assume <expr> ;
             | id = random ;
             | id = <expr> ;
             | id = id ( <var_list> ) ;
             | ( <var_list> ) = id ( <var_list> ) ;
             | if <bexpr> then <statement>+ [else <statement>+ ] endif ;
             | while <bexpr> do <statement>+ done ;
<var_list> ::=  $\epsilon$  | id ( , id)*

```

The `skip` operation does nothing. The `halt` operation halts the program execution. The `fail` has exactly the same operational semantics, but, in addition, indicates a final control point for backward analysis (see below).

The `assume expr` instruction is equivalent to `if expr then skip; else halt;`. It may be used to abstract non-deterministic assignments. For instance, the non-deterministic assignment of a value between 0 and 2 to a variable `x` can be written as

```

x = random;
assume x>=0 and x<=2;

```

A call to a procedure with a single return value can be written either as `x = P(...)` or `(x)=P(...)`. A call to a procedure with multiple return values is written as `(x,y) = P(a,b)`. Input parameters are passed by value. Formal input parameters in a procedure are assumed immutable.

Conditional and iteration constructions have the usual semantics.

### 2.1.3 Expressions.

#### Expressions.

```

<expr> ::= random  random value (type deduced from the context)
        | <bexpr>   Boolean expression
        | <iexpr>   bounded integer expression
        | <eexpr>   enumerated type expression
        | <nexpr>   numerical expression

```

## Boolean expressions.

```
<bexpr> ::= true | false
          | id                               variable
          | <constraint>
          | not <bexpr>
          | <bexpr> (or | and) <bexpr>
          | ( <bexpr> )
          | if <bexpr> then <bexpr> else <bexpr>
<constraint> ::= id == <expr>
               <iexpr> (>= | > | <= | <) <iexpr>
               <nexpr> (>= | > | <= | <) <nexpr>
```

Atoms of Boolean expressions are Boolean constants or equality constraints (on any type) or inequality constraints over bounded integer or numerical variables.

## Bounded integer and enumerated expressions.

```
<iexpr> ::= uint [<integer>] (<integer>)      constant (second integer) of given type
          | sint [<integer>] (<integer>)      constant (second integer) of given type
          | id                                 variable
          | <iexpr> (+|-|*) <iexpr>
          | ( <iexpr> )
          | if <bexpr> then <iexpr> else <iexpr>
<eexpr> ::= id                                 variable or constant (label)
          | ( <eexpr> )
          | if <bexpr> then <eexpr> else <eexpr>
```

Example:

```
/* Illustrate enumerated and bounded integer types */
typedef t = enum a,b,c,d,e ;

var x:sint[4],y:sint[4], z:t;

begin
  x = sint[4](2);
  y = random;
  z = a;
  if x==y then
    x = x + x;
    x = x-sint[4](3)*y;
    z = b;
  endif;
  if x<=y then
    z = e;
  endif;
  if z==d then z=c; endif;
end
```

## Numerical expressions.

```
<nexpr> ::= <coeff>
          | id                               variable
          | <unop> <nexpr> | <nexpr> <binop> <nexpr>
          | ( <nexpr> )
          | if <bexpr> then <nexpr> else nexpr
<binop> ::= (+|-|*|/|%)[_(i|f|d|l|q)[,(n|0|+oo|-oo)]]
<unop>  ::= -
          | (cast|sqrt)[_(i|f|d|l|q)[,(n|0|+oo|-oo)]]
<coeff> ::= <float> | <rational>
<float> ::= C/OCaml floating-point number syntax
<rational> ::= <integer> | <integer>/<integer>
```

The syntax of numerical expressions is the same as the one used in the APRON interactive toplevel (in OCaml language).

The priorities between (Boolean and arithmetic) operators is  $\{ *, / \} > \{ +, - \} > \{ <, <=, =, >=, > \} > \{ \text{not} \} > \{ \text{and} \} > \{ \text{or} \}$

By default, numerical expressions are evaluated using exact arithmetic on real numbers (even if some involved variables are integer), and when assigned to a variable, filtered by the variable domain (when it is integers). For instance, the assignment

```
x = 3/4;
```

is equivalent to the `halt` instruction if `x` is declared as integer, because the rational  $3/4$  is not an integer value. The problem here is that the instruction is not well-typed (even if this is not checked). If one want to emulate the semantics of the integer division operation, with rounding to zero, one should write

```
x = 3 /_i,0 4;
```

Indeed, most arithmetic operators have optional qualifiers that allows to modify their semantics. The first qualifier indicates a numerical type, the second one the rounding mode.

- By default, operations have an exact arithmetic semantics in the real numbers (even if involved variables are of integer).

The type qualifiers modify this default semantics. Their meaning is as follows:

```
i  integer semantics
f  IEEE754 32 bits floating-point semantics
d  IEEE754 64 bits floating-point semantics
l  IEEE754 80 bits extended floating-point semantics
q  IEEE754 128 bits floating-point semantics
```

- By default, the rounding mode is “any” (this applies only in non-real semantics), which allows to emulate all the following rounding modes:

```
n  nearest
0  towards zero
+oo towards infinity
-oo towards minus infinity
```

## Examples of numerical expressions.

We illustrate the syntax and (approximated) semantics of numerical expressions with the following program, annotated by InterprocStack using the command

```
interprocstack.opt -domain polka -colorize false examples/numerical.spl
```

```
proc integer () returns () var a : int, b : int, c : int;
begin
  /* (L5 C5) top */
  a = 5; /* (L6 C8) [|a-5=0|] */
  b = 2; /* (L7 C8) [|b-2=0; a-5=0|] */
  if brandom then
    /* (L8 C17) [|b-2=0; a-5=0|] */
    c = a / b; /* (L9 C14) bottom */
  else
    /* (L10 C6) [|b-2=0; a-5=0|] */
    c = a /_i,? b; /* (L11 C16) [|b-2=0; a-5=0; -c+3>=0; c-2>=0|] */
    c = a /_i,0 b; /* (L12 C18) [|c-2=0; b-2=0; a-5=0|] */
    c = a /_i,-oo b; /* (L13 C20) [|c-2=0; b-2=0; a-5=0|] */
    c = a /_i,+oo b; /* (L14 C20) [|c-3=0; b-2=0; a-5=0|] */
    c = a /_i,n b; /* (L15 C18) [|b-2=0; a-5=0; -c+3>=0; c-2>=0|] */
    c = a %_i,? b; /* (L16 C16) [|c-1=0; b-2=0; a-5=0|] */
  endif; /* (L17 C8) [|c-1=0; b-2=0; a-5=0|] */
end

proc exact () returns (z : real) var x : real, y : real;
begin
  /* (L22 C5) top */
  x = 5; /* (L23 C8) [|x-5=0|] */
  y = 2; /* (L24 C8) [|y-2=0; x-5=0|] */
  z = x / y; /* (L25 C10) [|2z-5=0; y-2=0; x-5=0|] */
  y = 0.1; /* (L26 C10)
    [|2z-5=0; 36028797018963968y-3602879701896397=0; x-5=0|] */
  z = x + y; /* (L27 C10)
    [|36028797018963968z-183746864796716237=0;
    36028797018963968y-3602879701896397=0; x-5=0|] */
  z = z - y; /* (L28 C10)
    [|z-5=0; 36028797018963968y-3602879701896397=0; x-5=0|] */
end

proc floating () returns (z : real) var x : real, y : real;
begin
  /* (L33 C5) top */
  x = 5; /* (L34 C8) [|x-5=0|] */
  y = 2; /* (L35 C8) [|y-2=0; x-5=0|] */
  z = x /_f,? y; /* (L36 C13)
    [|y-2=0; x-5=0;
    -713623846352979940529142984724747568191373312z
    +1784059828558929176909397126420998565333565441>=0;
    713623846352979940529142984724747568191373312z
    -1784059403205970525736317797202739275623301119>=0|] */
  y = 0.1; /* (L37 C10)
    [|36028797018963968y-3602879701896397=0; x-5=0;
    -713623846352979940529142984724747568191373312z
    +1784059828558929176909397126420998565333565441>=0;
    713623846352979940529142984724747568191373312z
    -1784059403205970525736317797202739275623301119>=0|] */
  z = x +_f,? y; /* (L38 C14)
    [|36028797018963968y-3602879701896397=0; x-5=0;
    -713623846352979940529142984724747568191373312z
```

```

+3639482050260215524856578735848702239922192385>=0;
713623846352979940529142984724747568191373312z
-3639481182540179876463495959770156714984210431>=0] */
z = z -_f,? y; /* (L39 C14)
[136028797018963968y-3602879701896397=0; x-5=0;
-5986310706507378352962293074805895248510699696029696z
+29931560882862943060522688904967984086376852368654337>=0;
5986310706507378352962293074805895248510699696029696z
-29931546182211708189135890236173744477275669529624577>=0]] */
end

var z : real
begin
  /* (L43 C5) top */
  () = integer(); /* (L44 C17) top */
  z = exact(); /* (L45 C14) [z-5=0] */
  z = floating(); /* (L46 C17)
[ -5986310706507378352962293074805895248510699696029696z
+29931560882862943060522688904967984086376852368654337>=0;
5986310706507378352962293074805895248510699696029696z
-29931546182211708189135890236173744477275669529624577>=0]] */
end

```

## 2.2 Formal semantics (to be updated)

We give here the standard operational semantics of the “Simple” language.

### 2.2.1 Semantics domains.

They are summarized by the following table:

$k \in K$	program’s control points
$\epsilon \in \mathbf{Env} = \mathbf{Var} \rightarrow \mathbb{R}$	environments
$(k, \epsilon) \in K \times \mathbf{Env}$	activation records
$s \in S = (K \times \mathbf{Env})^+$	program states, which are non-empty stacks

An environment is defined by a function assigning a value to a set of variables **Var** visible in the current scope.

A program state is a non-empty stack of activation records. A stack is viewed as a word where the last letter corresponds to the top of the stack.

### 2.2.2 Semantics of expressions.

The semantics of a numerical expression **nexpr** is a function

$$\llbracket \mathbf{nexpr} \rrbracket^n : \mathbf{Env} \rightarrow \wp(\mathbb{R})$$

We refer to [1] for the precise definition of this semantic function.

The semantics of a Boolean expression **bexpr** is a function

$$\llbracket \mathbf{bexpr} \rrbracket^b : \mathbf{Env} \rightarrow \wp(\mathbb{B})$$

which is defined inductively as follows:

$$\begin{aligned}
\llbracket \text{true} \rrbracket^b &= \lambda \epsilon . \{ \text{true} \} \\
\llbracket \text{false} \rrbracket^b &= \lambda \epsilon . \{ \text{false} \} \\
\llbracket \text{brandom} \rrbracket^b &= \lambda \epsilon . \{ \text{true}, \text{false} \} \\
\llbracket \text{not } e \rrbracket^b &= \lambda \epsilon . \{ \neg b \mid b \in \llbracket e \rrbracket^b(\epsilon) \} \\
\llbracket e_1 \text{ and } e_2 \rrbracket^b &= \lambda \epsilon . \{ b_1 \wedge b_2 \mid b_1 \in \llbracket e_1 \rrbracket^b(\epsilon) \wedge b_2 \in \llbracket e_2 \rrbracket^b(\epsilon) \} \\
\llbracket e_1 \text{ or } e_2 \rrbracket^b &= \lambda \epsilon . \{ b_1 \vee b_2 \mid b_1 \in \llbracket e_1 \rrbracket^b(\epsilon) \wedge b_2 \in \llbracket e_2 \rrbracket^b(\epsilon) \} \\
\llbracket e_1 \text{ op } e_2 \rrbracket^b &= \llbracket (e_1 - e_2) \text{ op } 0 \rrbracket^b \\
\llbracket e = 0 \rrbracket^b &= \lambda \epsilon . (0 \in \llbracket e \rrbracket^n(\epsilon)) \\
\llbracket e \geq 0 \rrbracket^b &= \lambda \epsilon . (\llbracket e \rrbracket^n(\epsilon) \cap [0, \infty] \neq \emptyset) \\
\llbracket e \leq 0 \rrbracket^b &= \lambda \epsilon . (\llbracket e \rrbracket^n(\epsilon) \cap ]-\infty, 0] \neq \emptyset) \\
\llbracket e > 0 \rrbracket^b &= \lambda \epsilon . (\llbracket e \rrbracket^n(\epsilon) \cap ]0, \infty] \neq \emptyset) \\
\llbracket e < 0 \rrbracket^b &= \lambda \epsilon . (\llbracket e \rrbracket^n(\epsilon) \cap ]-\infty, 0[ \neq \emptyset)
\end{aligned}$$

The semantics of a Boolean expression can be extended as a predicate on environments as follows:

$$\begin{aligned}
\llbracket \text{bexpr} \rrbracket^b : \mathbf{Env} &\rightarrow \mathbb{B} \\
\epsilon &\mapsto (\text{true} \in \llbracket \text{bexpr} \rrbracket^b)
\end{aligned}$$

### 2.2.3 Semantics of programs

We define the semantics of a program as a discrete dynamical system  $(\mathcal{S}, \mathcal{S}_0, \rightarrow)$  where  $\mathcal{S}$  is the state-space of the program (see above),  $\mathcal{S}_0$  is the set of initial states, and  $\rightarrow$  is the transition relation between states.

If  $k_0$  denotes the starting point of the main procedure, then  $\mathcal{S}_0$  is defined as

$$\mathcal{S}_0 = \{k_0\} \times \mathbf{Env}$$

This reflects the hypothesis that variables are uninitialized (read: they may contain arbitrary values) at start.

The transition relation is defined as follows:

$$\begin{aligned}
&\frac{(k) \text{ skip } (k')}{\omega \cdot (k, \epsilon) \rightarrow \omega \cdot (k', \epsilon)} \quad \frac{(k) \text{ assume } \text{bexpr} (k') \quad \text{true} \in \llbracket \text{bexpr} \rrbracket^b(\epsilon)}{\omega \cdot (k, \epsilon) \rightarrow \omega \cdot (k', \epsilon)} \\
&\frac{(k) \text{ x=random } (k') \quad \forall y \in \mathbf{Var} \setminus \{x\} : \epsilon'(y) = \epsilon(y)}{\omega \cdot (k, \epsilon) \rightarrow \omega \cdot (k', \epsilon')} \\
&\frac{(k) \text{ x=nexpr } (k') \quad v \in \llbracket \text{nexpr} \rrbracket^n(\epsilon)}{\omega \cdot (k, \epsilon) \rightarrow \omega \cdot (k', \epsilon[x \mapsto v])} \\
&\frac{(k) \text{ if } \text{bexpr} \text{ then } (k_1) \dots (k'_1) \text{ else } (k_2) \dots (k'_2) ; (k')}{\begin{aligned} &(k, \epsilon) \rightarrow (k_1, \epsilon) \text{ if } \text{true} \in \llbracket \text{bexpr} \rrbracket^b(\epsilon) \\ &(k, \epsilon) \rightarrow (k_2, \epsilon) \text{ if } \text{false} \in \llbracket \text{bexpr} \rrbracket^b(\epsilon) \\ &(k'_1, \epsilon) \rightarrow (k', \epsilon) \\ &(k'_2, \epsilon) \rightarrow (k', \epsilon) \end{aligned}} \\
&\frac{(k) \text{ while } \text{bexpr} \text{ do } (k_1) \dots (k'_1) \text{ done } (k_2)}{\begin{aligned} &(k, \epsilon) \rightarrow (k_1, \epsilon) \text{ if } \text{true} \in \llbracket \text{bexpr} \rrbracket^b(\epsilon) \\ &(k, \epsilon) \rightarrow (k_2, \epsilon) \text{ if } \text{false} \in \llbracket \text{bexpr} \rrbracket^b(\epsilon) \\ &(k'_1, \epsilon) \rightarrow (k, \epsilon) \end{aligned}}
\end{aligned}$$



$$\begin{array}{c}
(k) \ (y_0, \dots, y_N) = f(x_0, \dots, x_M) \ (k') \\
\epsilon_{\text{start}}(\vec{p} \vec{i} \vec{n}) = \epsilon(\vec{x}) \\
\epsilon' = \epsilon[\vec{y} \mapsto \epsilon_{\text{exit}}(\vec{p} \vec{o} \vec{u} \vec{t})] \\
\hline
\omega \cdot (k, \epsilon) \rightarrow \omega \cdot (k', \epsilon) \cdot (k_{\text{start}}^f, \epsilon_{\text{start}}) \\
\omega \cdot (k', \epsilon) \cdot (k_{\text{exit}}^f, \epsilon_{\text{exit}}) \rightarrow \omega \cdot (k', \epsilon')
\end{array}$$

### 3 What InterprocStack does for you

InterprocStack takes as input a “Simple” program, annotates it with control points, perform forward and/or backward analysis, and print the annotated programs with invariants associated with each control point, like this:

Annotated program after forward analysis:

```

var x : int, y : int, z : int
begin
  /* (L5 C5) top */
  assume z >= 10 and z <= 20; /* (L6 C25) [| -z+20 >= 0; z-10 >= 0 |] */
  x = 0; /* (L7 C8) [| x=0; -z+20 >= 0; z-10 >= 0 |] */
  y = 0; /* (L7 C13) [| -3x+y=0; -x+z+1 >= 0; -z+20 >= 0; z-10 >= 0; x >= 0 |] */
  while x <= z do
    /* (L8 C17) [| -3x+y=0; -x+z >= 0; -z+20 >= 0; z-10 >= 0; x >= 0 |] */
    x = x + 1; /* (L9 C12)
                [| -3x+y+3=0; -x+z+1 >= 0; -z+20 >= 0; z-10 >= 0; x-1 >= 0 |] */
    y = y + 3; /* (L10 C12) [| -3x+y=0; -x+z+1 >= 0; -z+20 >= 0; z-10 >= 0; x-1 >= 0 |] */
  done; /* (L11 C7) [| -3x+y=0; -x+z+1 >= 0; -x+21 >= 0; x-11 >= 0 |] */
  if y >= 42 then
    /* (L12 C15) [| -3x+y=0; -x+z+1 >= 0; -x+21 >= 0; x-14 >= 0 |] */
    fail; /* (L13 C9) bottom */
  endif; /* (L14 C8) [| -3x+y=0; -x+z+1 >= 0; -3x+41 >= 0; x-11 >= 0 |] */
end

```

#### Invariants

An *invariant*  $I$  is a set of environments:

$$I \in \wp(\text{Env})$$

The result of the analyses performed by InterprocStack is the projection  $p(\mathbf{X})$  of sets of stacks on their top elements. The result of this projection is a function that maps control point to invariants:

$$\begin{array}{ccc}
p : \wp((K \times \text{Env})^+) & \longrightarrow & (K \rightarrow \wp(\text{Env})) \\
\mathbf{X} & \longmapsto & \lambda k . \{ \epsilon \mid \omega \cdot (k, \epsilon) \in \mathbf{X} \}
\end{array}$$

Intuitively, the invariant on numerical variables associated with each program point, as returned by InterprocStack, indicates the possible values for these variables at each program point, for any stack tail.

#### Single forward/reachability analysis

A forward analysis compute the set of reachable states of the program, which is defined as:

$$\text{Reach} = \{ s \in S \mid s_0 \in S_0 \wedge s_0 \rightarrow^* s \}$$

InterprocStack returns an overapproximation of  $p(\text{Reach})$ .

## Single backward/coreachability analysis

A backward analysis computes the set of states from which one can reach a `fail` instruction.

The set of states coreachable from a `fail` instruction is defined as:

$$\mathit{Coreach} = \{s \in S \mid s \rightarrow^* s_f \wedge s_f \in F\}$$

with the set of final states

$$F = \{\omega \cdot (k, \epsilon) \mid k \in K_{\text{fail}} \wedge \epsilon \in \text{Env}\}$$

where  $K_{\text{fail}}$  is the set of control points just preceding `fail` instructions. `InterprocStack` returns an overapproximation of  $p(\mathit{Coreach})$ .

## Combined forward/backward analyses

`InterprocStack` allows to combine forward and backward analysis any number of time.

If  $X$  denotes the invariant computed by `InterprocStack` at the previous step, at the current step:

- a forward analysis will consider the set of initial states

$$S_0 \cap p^{-1}(X)$$

- a backward analysis will consider the set of final states

$$F \cap p^{-1}(X)$$

For instance, after executing the command

```
interprocstack -analysis fb essai.spl
```

on the previous program, we get

Annotated program after forward analysis

```
var x : int, y : int, z : int
begin
  /* (L5 C5) top */
  assume z >= 10 and z <= 20; /* (L6 C25) [| -z+20 >= 0; z-10 >= 0|] */
  x = 0; /* (L7 C8) [| x=0; -z+20 >= 0; z-10 >= 0|] */
  y = 0; /* (L7 C13) [| -3x+y=0; -x+z+1 >= 0; -z+20 >= 0; z-10 >= 0; x >= 0|] */
  while x <= z do
    /* (L8 C17) [| -3x+y=0; -x+z >= 0; -z+20 >= 0; z-10 >= 0; x >= 0|] */
    x = x + 1; /* (L9 C12)
               [| -3x+y+3=0; -x+z+1 >= 0; -z+20 >= 0; z-10 >= 0; x-1 >= 0|] */
    y = y + 3; /* (L10 C12) [| -3x+y=0; -x+z+1 >= 0; -z+20 >= 0; z-10 >= 0; x-1 >= 0|] */
  done; /* (L11 C7) [| -3x+y=0; -x+z+1=0; -x+21 >= 0; x-11 >= 0|] */
  if y >= 42 then
    /* (L12 C15) [| -3x+y=0; -x+z+1=0; -x+21 >= 0; x-14 >= 0|] */
    fail; /* (L13 C9) bottom */
  endif; /* (L14 C8) [| -3x+y=0; -x+z+1=0; -3x+41 >= 0; x-11 >= 0|] */
end
```

Annotated program after backward analysis

```
var x : int, y : int, z : int
begin
  /* (L5 C5) [| -z+20 >= 0; z-13 >= 0|] */
  assume z >= 10 and z <= 20; /* (L6 C25) [| -z+20 >= 0; z-13 >= 0|] */
```

```

x = 0; /* (L7 C8) [|x=0; -z+20>=0; z-13>=0|] */
y = 0; /* (L7 C13) [| -3x+y=0; -x+z+1>=0; -z+20>=0; z-13>=0; x>=0|] */
while x <= z do
  /* (L8 C17) [| -3x+y=0; -x+z>=0; -z+20>=0; z-13>=0; x>=0|] */
  x = x + 1; /* (L9 C12)
              [| -3x+y+3=0; -x+z+1>=0; -z+20>=0; z-13>=0; x-1>=0|] */
  y = y + 3; /* (L10 C12) [| -3x+y=0; -x+z+1>=0; -z+20>=0; z-13>=0; x-1>=0|] */
done; /* (L11 C7) [| -3x+y=0; -x+z+1=0; -x+21>=0; x-14>=0|] */
if y >= 42 then
  /* (L12 C15) [| -3x+y=0; -x+z+1=0; -x+21>=0; x-14>=0|] */
  fail; /* (L13 C9) bottom */
endif; /* (L14 C8) bottom */
end

```

## References

- [1] A. Miné. *Domaines numériques abstraits faiblement relationnels (Weakly relational numerical abstract domains)*. PhD thesis, École Normale Supérieure de Paris, 2004. PDF.